



SeaTalk(1) and SeaTalk(ng) is getting 12V from Course computer via ST6002 and ST60 Tridata.

The backbone is terminated in both ends.

Axiom 7 DV are communicating with transducer speed/depth, but the slide-switch Pilotcontrol is not active.

Is the solution to remove output SeaTalk(1) on the Smartpilot and connect Smartpilot output Seataalk(ng)to Seataalk(ng) and connect 12V to the Backbone.

